

# MRI-compliant piezo micro-actuator

4th Summer School on Surgical Robotics

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# Myself

- French
- Mechanical and Design Engineer
- Special PhD: CIFRE (Uni. Lab. + Company)



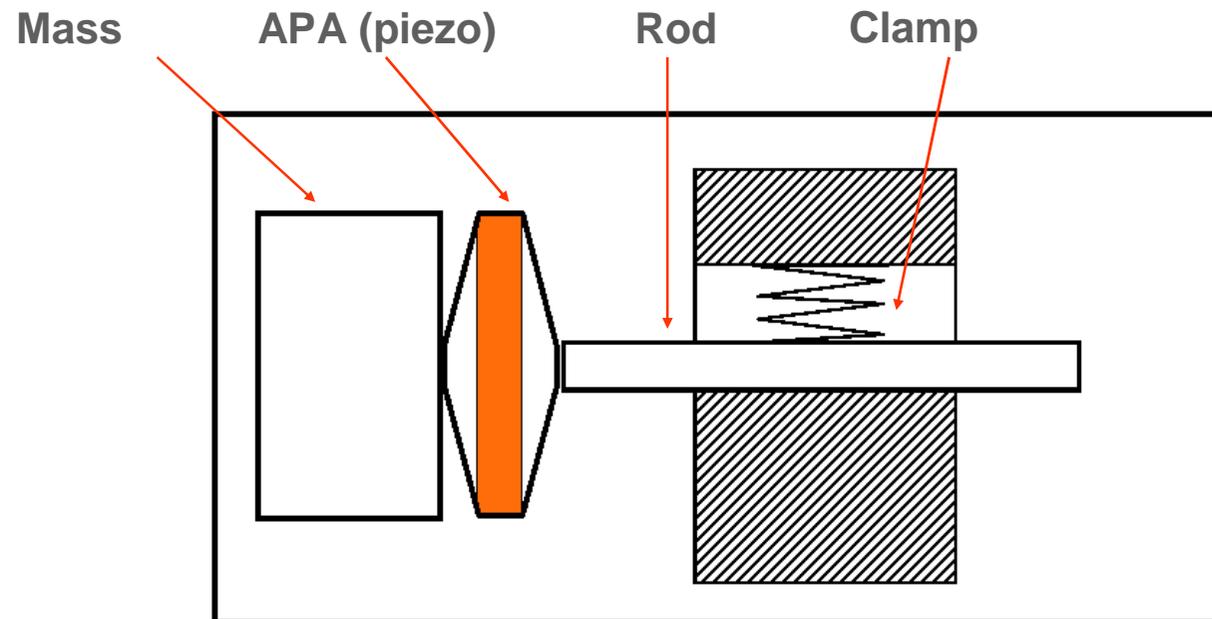
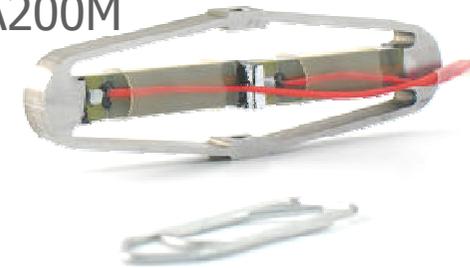
- Subject: Inertial Piezo Motor: Design, tests and applications

# Stepping Piezo Actuator

## What is it?

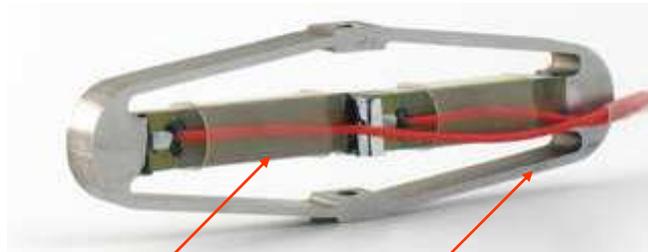
- » Linear piezo motor
  - ✓ Long stroke
  - ✓ High resolution
- » Components:

APA200M



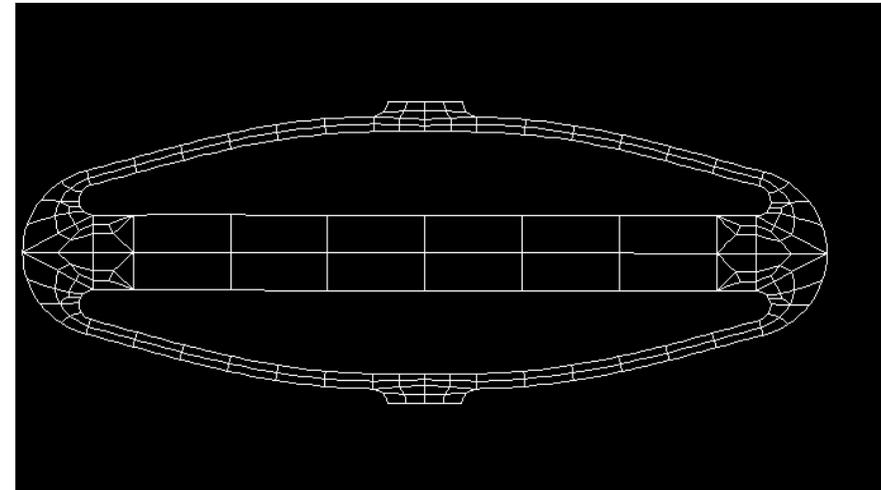
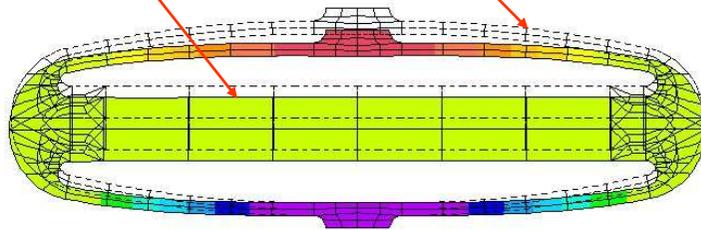
# Amplified Piezo Actuator

## ● APA Amplified Piezo Actuators



Piezo ceramic

Shell to amplify & prestress



ATILA FEM, accounting for piezo coupling

- » APAs are compatible with non-magnetism & cryo, vacuum environments ...

# Stepping Piezo Actuator

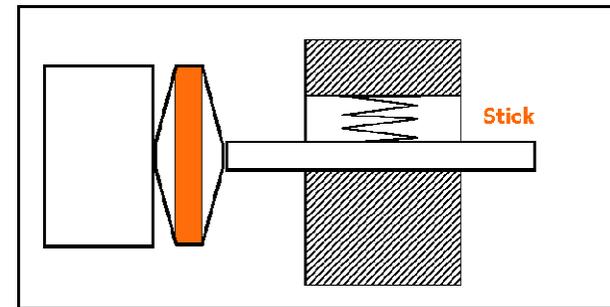
## How does it work?

### » 2 working modes

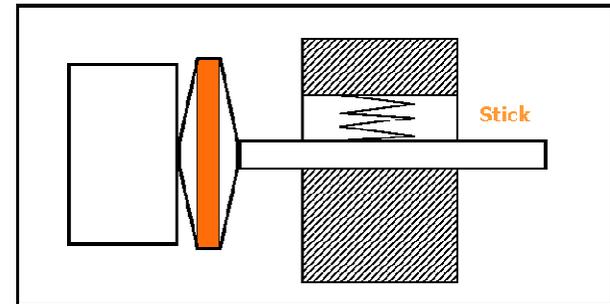
- ✓ Stepping mode (M1)
  - Saw tooth signal
  - Stick-slip of the rod in the clamp
- ✓ Deformation mode (M2)
  - Load fixed on the Mass
  - APA deformation proportional to voltage

### » 2 complementary modes

- ✓ Important stroke/resolution ratio



Stepping Mode

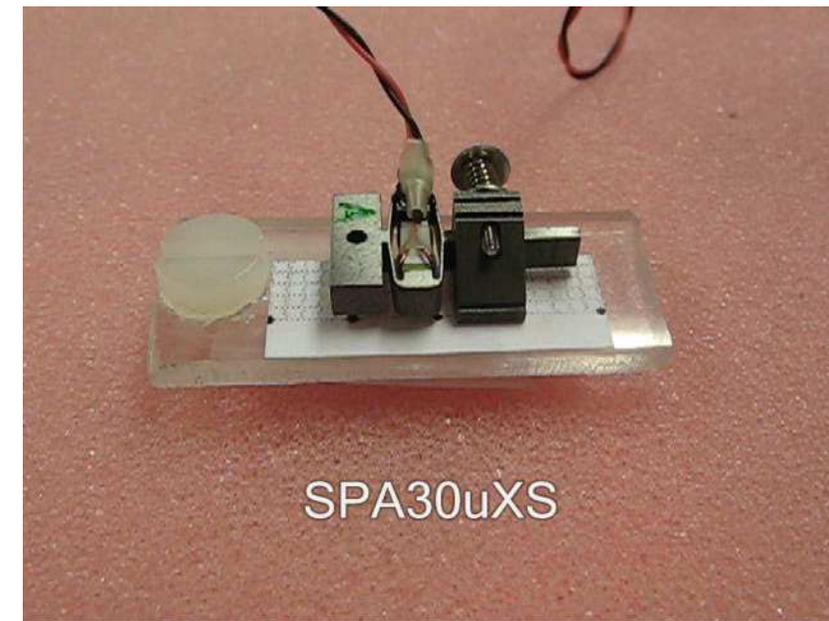
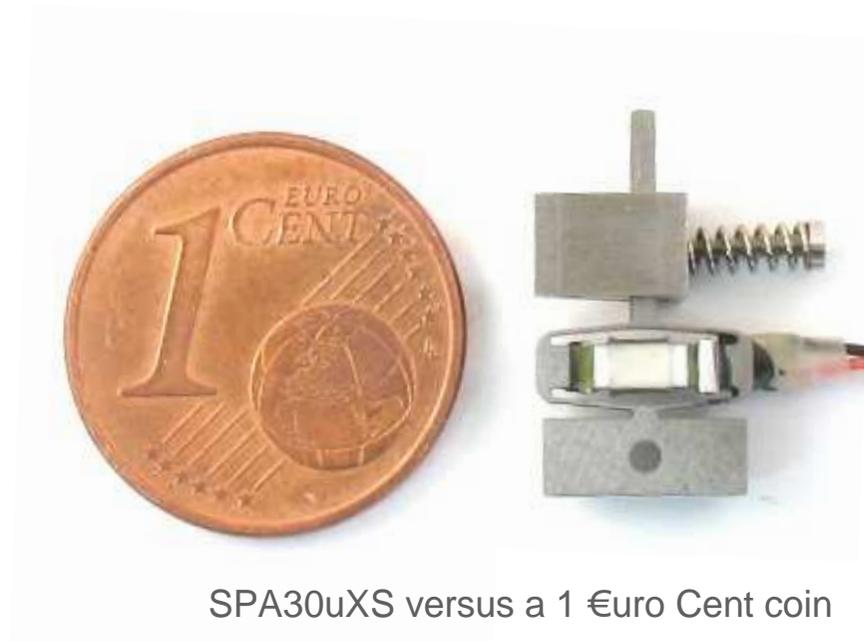
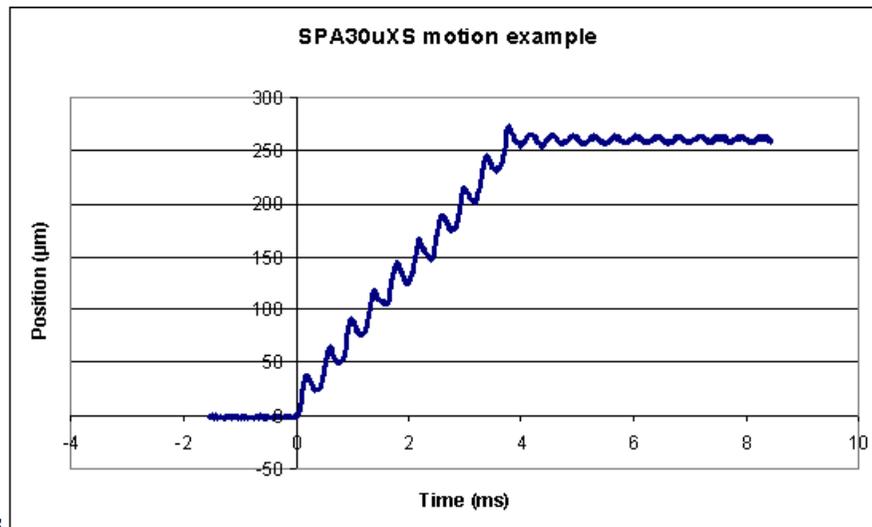


Deformation Mode

# Prototype

## ● SPA30uXS

- » Mass < 2 grams
- » Volume < 500 mm<sup>3</sup>
- » Stroke = 4mm
- » Resolution < 5nm
- » Speed : Up to 70 mm/s
- » Force : Up to 0,2 N

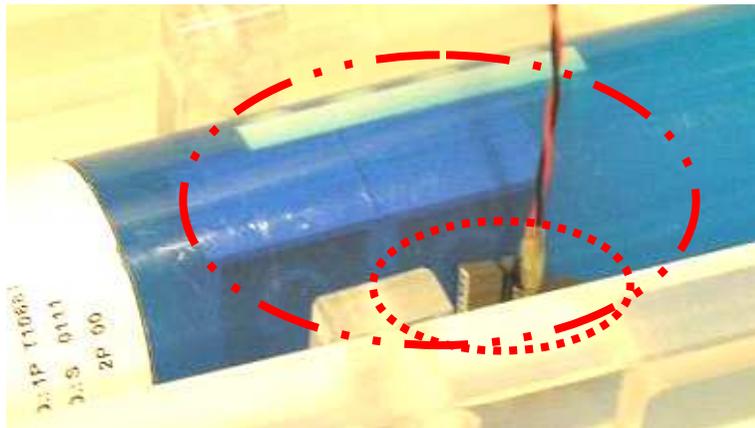


# MRI-compatibility

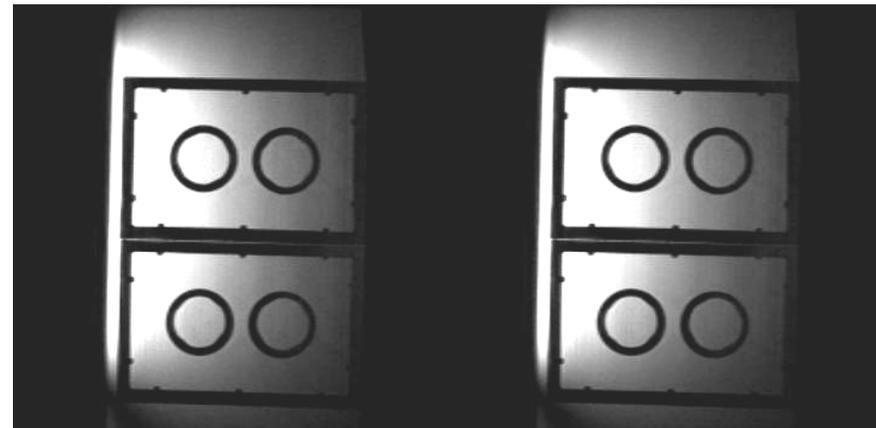
## ● Non-magnetic actuator

### » Tests performed into an MRI 4,7 Tesla magnet

- ✓ Is not attracted by the magnet (safety)
- ✓ It does not perturb the MRI image SNR, even when moving
- ✓ Performances are not affected by magnet: need a sensor adapted



Actuator position (dot) against measured position (dashed)



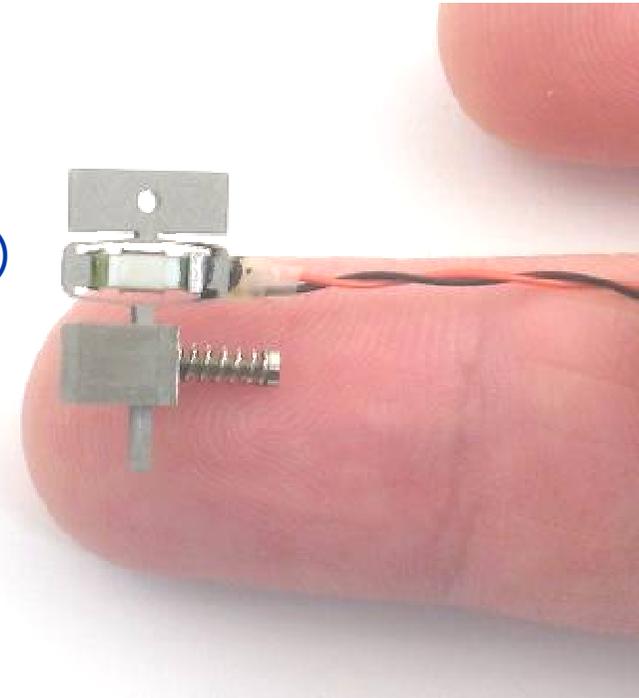
Ghost capture without and with actuator in the field of view

*These tests have been performed on Small Animals platform, INSERM Grenoble, France*

## Conclusion

- SPA quick facts

- » Tiny motor
- » Total control of the speed
- » High maximum speed (Up to 70 mm/s)
- » Holding force with no consumption
- » MRI compatible



Thank you

Feel free to ask questions



Laboratoire Mécatronique  
Méthodes, Modèles et Métiers

